**(GDD)**

LED String Animation

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# **Document History**

## **Current Document Status**

|  |  |  |  |
| --- | --- | --- | --- |
| Version | Status | Author | **Date** |
| 1.0 | Draft | Caroline - Mark | 28/02/2020 |
| 1.2 | Draft | Caroline | 28/2/2020 |

## **Revision History Table**

|  |  |  |  |
| --- | --- | --- | --- |
| Version | Author | Date | Change |
| 1.0 | Caroline - Mark | 28/02/2020 | Initial Creation |
| 1.2 | Caroline | 28/2/2020 | Added DIO APIs |

# **Reference Documents Table**

|  |  |  |  |
| --- | --- | --- | --- |
| Ref. number | Doc. Name | Version | Status |
| 1 | LED\_STRING\_ANIMATION\_CYRS | 1.6 | Proposed |
| 2 | LED\_String\_HSI | 1.6 | Proposed |

# **Project Description**

The project is composed of 3 sets of LED Strings Simulating the animation of LEDs in a Car, One set is named “Tail” and it simulates the animation of car’s back LEDs while the other 2 sets are named “Left TI” and “Right TI” is simulating the animation of left and right turn indicator in a car.

Each one of the 3 functions operates based on input signals coming from 3 switches named “Tail Switch”, “Left TI” and “Right TI” respectively in addition to “Welcome Mode” which shall operates one of 2 different modes based on the status of the mode switch. System layout is as shown in **Figure 1** below.



Figure 1: layout of the system

# **Software Context Diagram**

LEDs Manager

Switches Status

Handler

LEDs Status

LED Handler

Switch Manager

# **Input Output Signals**

* Mode Signal

LED Animation Algorithm

Signal\_Mode

Signal\_LEDsData

LEDs

Mode

Switch

|  |  |  |
| --- | --- | --- |
| Signal | Range | Unit |
| Signal\_Mode | 0-1 | Uint8\_t |
| Signal\_LEDsData | - | LEDString\_t |

* TIR Signal

Signal\_LEDsData

Signal\_TIR\_Mode

LED Animation Algorithm

LEDs

TIR

Switch

|  |  |  |
| --- | --- | --- |
| Signal | Range | Unit |
| Signal\_TIR\_Mode | 0-1 | Uint8\_t |
| Signal\_LEDsData | - | LEDString\_t |

* TIL Signal

Signal\_LEDsData

Signal\_TIL\_Mode

LED Animation Algorithm

LEDs

TIL

Switch

|  |  |  |
| --- | --- | --- |
| Signal | Range | Unit |
| Signal\_TIL\_Mode | 0-1 | Uint8\_t |
| Signal\_LEDsData | - | LEDString\_t |

* Tail Signal

Signal\_LEDsData

Signal\_Tail\_Mode

LED Animation Algorithm

LEDs

Tail

Switch

|  |  |  |
| --- | --- | --- |
| Signal | Range | Unit |
| Signal\_Tail\_Mode | 0-1 | Uint8\_t |
| Signal\_LEDsData | - | LEDString\_t |

# **Software Features**

LEDs Control Features

Input Feature

Output Feature

Switches\_Status\_Signal

Signal\_Mode

Signal\_Tail\_Mode

Signal\_TIR\_Mode

Signal\_TIL\_Mode

Microcontroller Feature

# **Static Architecture**

APPLICATION

LIB

Std\_Types

LED\_Animation

HAL

Switch

LED

Bit\_Man

MCAL

DIO

# **APIs**

* LED\_Animation
* Types

|  |  |
| --- | --- |
| Name | LEDString\_t |
| Type | Structure |
| Range | - |
| Description | Data structure containing the set of configuration parameters required for setting the leds status |

|  |  |
| --- | --- |
| Name | LED\_Animation\_Tail\_State |
| Type | Enumeration |
| Range | LED\_ANIMATION\_TAIL\_ON |
| LED\_ANIMATION\_TAIL\_OFF |
| Description | The state of the tail LEDs |

|  |  |
| --- | --- |
| Name | LED\_Animation\_Running\_Mode |
| Type | Enumeration |
| Range | LED\_ANIMATION\_MODE\_WELCOME\_1 |
| LED\_ANIMATION\_MODE\_WELCOME \_2 |
| LED\_ANIMATION\_MODE\_TI\_1 |
| LED\_ANIMATION\_MODE\_TI\_2 |
| LED\_ANIMATION\_MODE\_NONE |
| Description | The state of the tail LEDs |

* Function definitions

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidInit |
| Parameters | None |
| Return Value | None |
| Description | Initializes all the LEDs and Switches required for the application |

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidSetFlags |
| Parameters | None |
| Return Value | None |
| Description | Reads all the switches status and sets all the flags that represents the LEDs animation |

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidStartAnimationMode |
| Parameters | None |
| Return Value | None |
| Description | Reads all the flags status and starts the suitable animation mode according to switches status |

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_03\_V01]**

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_04\_V01]**

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidSetTailLeds |
| Parameters | None |
| Return Value | None |
| Description | Sets the tail leds on and off according to the tail flag state |

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_01\_V01]**

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidRunModeOne |
| Parameters | None |
| Return Value | None |
| Description | Runs the animation of mode 1 which is described in the LED\_STRING\_ANIMATION\_CYRS |

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_02\_V01]**

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidRunModeTwo |
| Parameters | None |
| Return Value | None |
| Description | Runs the animation of mode 2 which is described in the LED\_STRING\_ANIMATION\_CYRS |

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_05\_V02]**

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_06\_V01]**

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidRunTI\_Right |
| Parameters | None |
| Return Value | None |
| Description | Runs the animation of TI right mode which is described in the LED\_STRING\_ANIMATION\_CYRS until the TI right switch is released |

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_07\_V02]**

**[Req\_ PO5\_LSAN\_ LED STRING ANIMATION\_08\_V01]**

|  |  |
| --- | --- |
| Name | LED\_Animation\_voidRunTI\_Left |
| Parameters | None |
| Return Value | None |
| Description | Runs the animation of TI left mode which is described in the LED\_STRING\_ANIMATION\_CYRS until the TI left switch is released |

|  |  |
| --- | --- |
| Name | DIO\_SetPinDir |
| Parameters | Port\_No , Pin\_No , Direction |
| Return Value | ErrorStatus |
| Description | Configures the Pin Direction Input/Output |

|  |  |
| --- | --- |
| Name | DIO\_SetPinVal |
| Parameters | Port\_No , Pin\_No , Value |
| Return Value | ErrorStatus |
| Description | Configures the Pin Value High/ Low |

|  |  |
| --- | --- |
| Name | DIO\_GetPinVal |
| Parameters | \*PTR\_Value |
| Return Value | ErrorStatus |
| Description | Reads the Pin Value High/Low |